Conjugate gradients method

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Strongly convex quadratics Consider the following quadratic optimization problem:

Optimality conditions

$$\min_{x \in \mathbb{R}^n} f(x) = \min_{x \in \mathbb{R}^n} \frac{1}{2} x^\top A x - b^\top x + c, \text{ where } A \in \mathbb{S}^n_{++}.$$
 (1) $Ax^* = b$

Steepest Descent Conjugate Gradient 4 4 2 2 0 C -2 -2 -4-4

 $\rightarrow \min$ Quadratic optimization problem

Exact line search aka steepest descent

$$\alpha_k = \arg\min_{\alpha \in \mathbb{R}^+} f(x_{k+1}) = \arg\min_{\alpha \in \mathbb{R}^+} f(x_k - \alpha \nabla f(x_k))$$

More theoretical than practical approach. It also allows you to analyze the convergence, but often exact line search can be difficult if the function calculation takes too long or costs a lot. An interesting theoretical property of this method is that each following iteration is orthogonal to the previous one:

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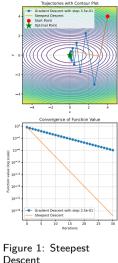
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Optimality conditions:

$$\nabla f(x_k)^T \nabla f(x_{k+1}) = 0$$

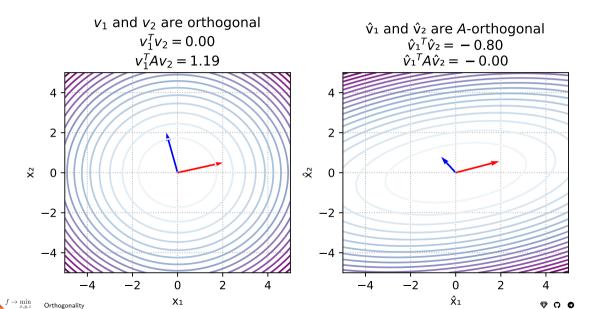
Optimal value for quadratics

$$\nabla f(x_k)^{\top} A(x_k - \alpha \nabla f(x_k)) - \nabla f(x_k)^{\top} b = 0$$
 $\alpha_k = \frac{\nabla f(x_k)^T \nabla f(x_k)}{\nabla f(x_k)^T A \nabla f(x_k)}$



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Suppose, we have two coordinate systems and some quadratic function $f(x) = \frac{1}{2}x^T I x$ looks just like on the left part of Figure 2, while in other coordinates it looks like $f(\hat{x}) = \frac{1}{2}\hat{x}^T A \hat{x}$, where $\tilde{A} \in \mathbb{S}^n_{++}$.

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♦ *A*-orthogonal vectors

Vectors $x \in \mathbb{R}^n$ and $y \in \mathbb{R}^n$ are called A-orthogonal (or A-conjugate) if

$$x^T A y = 0 \qquad \Leftrightarrow \qquad x \perp_A y$$

When A = I, A-orthogonality becomes orthogonality.

Input: *n* linearly independent vectors u_0, \ldots, u_{n-1} .

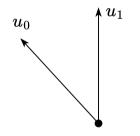


Figure 3: Illustration of Gram-Schmidt orthogonalization process



Input: *n* linearly independent vectors u_0, \ldots, u_{n-1} .

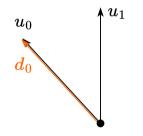


Figure 4: Illustration of Gram-Schmidt orthogonalization process



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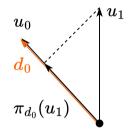


Figure 5: Illustration of Gram-Schmidt orthogonalization process



Input: *n* linearly independent vectors u_0, \ldots, u_{n-1} .

Output: *n* linearly independent vectors, which are pairwise orthogonal d_0, \ldots, d_{n-1} .

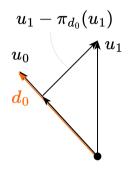


Figure 6: Illustration of Gram-Schmidt orthogonalization process



Input: *n* linearly independent vectors u_0, \ldots, u_{n-1} .

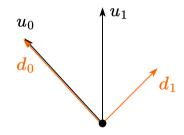
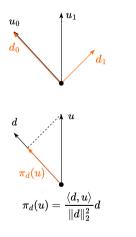
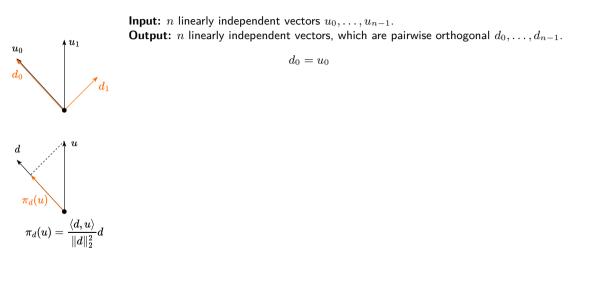


Figure 7: Illustration of Gram-Schmidt orthogonalization process

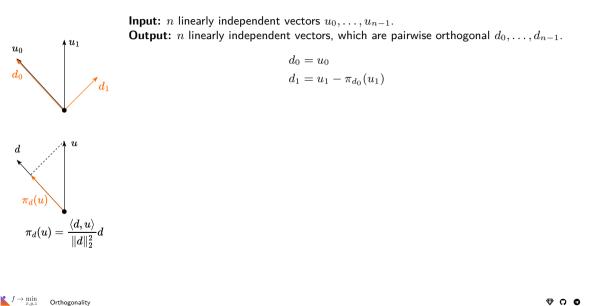


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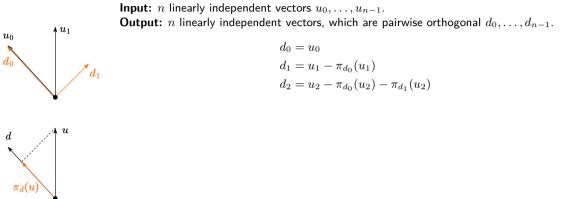




 $f \rightarrow \min_{x,y,z}$ Orthogonality

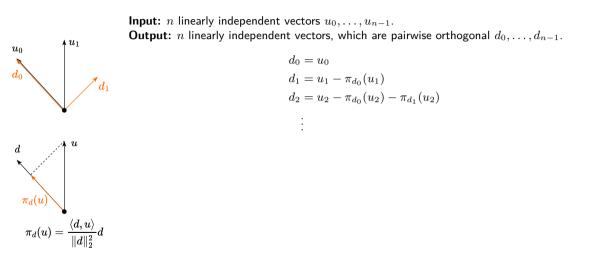


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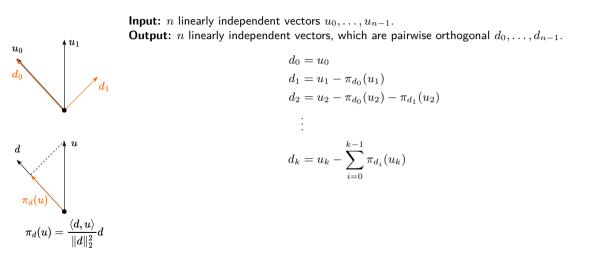


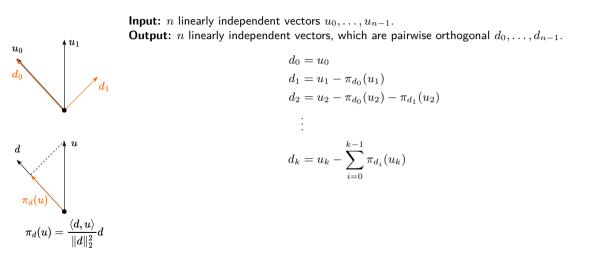
 $\pi_d(u) = rac{\langle d, u
angle}{\|d\|_2^2} d$

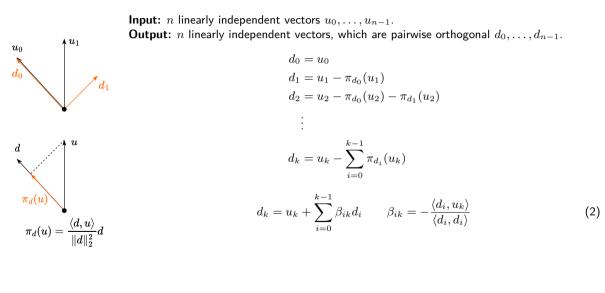










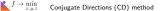


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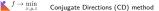
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• We will prove, that α_i and d_i could be selected in a very efficient way (Conjugate Gradient method).

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5. Repeat steps 2-4 until n directions are built, where n is the dimension of space (dimension of x).

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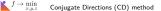
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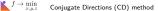


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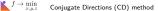
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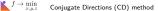
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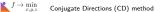
We'll show, that if $\sum_{i=1}^{n} \alpha_i d_i = 0$, than all coefficients should be equal to zero:

$$\begin{split} 0 &= \sum_{i=1}^{n} \alpha_{i} d_{i} \\ \text{Multiply by } d_{j}^{T} A \cdot &= d_{j}^{\top} A \left(\sum_{i=1}^{n} \alpha_{i} d_{i} \right) = \sum_{i=1}^{n} \alpha_{i} d_{j}^{\top} A d_{i} \\ &= \alpha_{j} d_{j}^{\top} A d_{j} + 0 + \ldots + 0 \end{split}$$

Thus, $\alpha_j = 0$, for all other indices one has to perform the same process

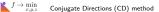
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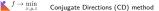
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• Note also, that since
$$x_{k+1} = x_0 + \sum_{i=1}^k \alpha_i d_i$$
, we have

$$e_{k+1} = e_0 + \sum_{i=1}^k \alpha_i d_i.$$
 (5)



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Suppose, we solve *n*-dimensional quadratic convex optimization problem (1). The conjugate directions method

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Proof

1. We need to prove, that $\delta_i = -\alpha_i$:

$$e_0 = x_0 - x^* = \sum_{i=0}^{n-1} \delta_i d_i$$

 $f \rightarrow \min_{x,y,z}$ Conjugate Directions (CD) method

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Suppose, we solve n-dimensional quadratic convex optimization problem (1). The conjugate directions method

$$x_{k+1} = x_0 + \sum_{i=0}^k \alpha_i d_i$$

with $\alpha_i = \frac{\langle d_i, r_i \rangle}{\langle d_i, A d_i \rangle}$ taken from the line search, converges for at most n steps of the algorithm.

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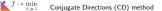
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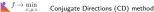
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$$\delta_{k} = \frac{d_{k}^{T} A e_{k}}{d_{k}^{T} A d_{k}} = -\frac{d_{k}^{T} r_{k}}{d_{k}^{T} A d_{k}} \Leftrightarrow \delta_{k} = -\alpha_{k}$$



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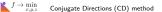
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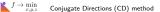
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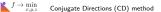
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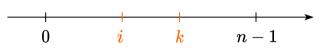
Proof

Let's write down (6) for some fixed index k:

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Multiply both sides by $-d_i^T A$.

$$-d_i^T A e_k = \sum_{j=k}^{n-1} \alpha_j d_i^T A d_j = 0$$



Thus, $d_i^T r_k = 0$ and residual r_k is orthogonal to all previous directions d_i for the CD method.



index

The idea of the Conjugate Gradients (CG) method

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- The main idea is that for an arbitrary CD method, the Gramm-Schmidt process is quite computationally expensive and requires a quadratic number of vector addition and scalar product operations $\mathcal{O}(n^2)$, while in the case of CG, we will show that the complexity of this procedure can be reduced to linear $\mathcal{O}(n)$.

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 $\mathsf{CG} = \mathsf{CD} + r_0, \ldots, r_{n-1}$ as starting vectors for Gram–Schmidt + A-orthogonality.



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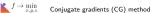
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 $r_k^T d_i = r_k^T u_i + \sum_{j=0}^{k-1} \beta_{ji} r_k^T d_j$

 $d_{i} = r_{i} + \sum_{\substack{j=0\\j \neq u_{i}}}^{k-1} \beta_{ji}d_{j} \quad \beta_{ji} = -\frac{\langle d_{j}, r_{i} \rangle_{A}}{\langle d_{j}, d_{j} \rangle_{A}} \quad \text{(10)} \quad \text{have:} \quad r_{k}^{T}u_{i} = 0 \quad \text{for CD} \quad r_{k}^{T}r_{i} = 0 \quad \text{for CG} \quad \nabla \mathcal{O} \quad \mathcal{O} \quad \mathbb{C}$

Moreover, if k = i:

$$r_k^T d_k = r_k^T u_k + \sum_{j=0}^{k-1} \beta_{jk} r_k^T d_j$$



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$$r_{k+1} = r_k - \alpha_k A d_k$$
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$$r_{k+1} = r_k - \alpha_k A d_k \tag{12}$$

$$r_{k+1} = -Ae_{k+1} = -A(e_k + \alpha_k d_k) = -Ae_k - \alpha_k Ad_k = r_k - \alpha_k Ad_k$$

Finally, all these above lemmas are enough to prove, that $\beta_{ji} = 0$ for all i, j, except the neighboring ones.

$$\beta_{ji} = -\frac{\langle d_j, u_i \rangle_A}{\langle d_j, d_j \rangle_A}$$

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Consider the Gram-Schmidt process in the CG method

$$\beta_{ji} = -\frac{\langle d_j, u_i \rangle_A}{\langle d_j, d_j \rangle_A} = -\frac{d_j^T A u_i}{d_j^T A d_j} = -\frac{d_j^T A r_i}{d_j^T A d_j} = -\frac{r_i^T A d_j}{d_j^T A d_j}$$

Consider the scalar product $\langle r_i, r_{j+1} \rangle$ using (12):

 $\langle r_i, r_{j+1} \rangle$

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$$\langle r_i, r_{j+1} \rangle = \langle r_i, r_j - \alpha_j A d_j \rangle$$

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$$\langle r_i, r_{j+1} \rangle = \langle r_i, r_j - \alpha_j A d_j \rangle = \langle r_i, r_j \rangle - \alpha_j \langle r_i, A d_j \rangle$$

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 $f \rightarrow \min_{x,y,z}$ Conjugate gradients (CG) method

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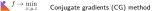
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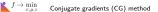
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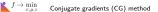
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And for the direction

$$d_{k+1} = r_{k+1} + \beta_{k,k+1} d_k, \qquad \beta_{k,k+1} = \beta_k = \frac{\langle r_{k+1}, r_{k+1} \rangle}{\langle r_k, r_k \rangle}.$$

 $f \rightarrow \min_{x,y,z}$ Conjugate gradients (CG) method

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Conjugate gradients method

 $\mathbf{r}_0 := \mathbf{b} - \mathbf{A}\mathbf{x}_0$ if \mathbf{r}_0 is sufficiently small, then return \mathbf{x}_0 as the result $\mathbf{d}_0 := \mathbf{r}_0$ k := 0repeat $\alpha_k := \frac{\mathbf{r}_k^\mathsf{T} \mathbf{r}_k}{\mathbf{d}_k^\mathsf{T} \mathbf{A} \mathbf{d}_k}$ $\mathbf{x}_{k+1} := \mathbf{x}_k + \alpha_k \mathbf{d}_k$ $\mathbf{r}_{k+1} := \mathbf{r}_k - \alpha_k \mathbf{A} \mathbf{d}_k$ if \mathbf{r}_{k+1} is sufficiently small, then exit loop $\beta_k := \frac{\mathbf{r}_{k+1}^{\mathsf{T}} \mathbf{r}_{k+1}}{\mathbf{r}_k^{\mathsf{T}} \mathbf{r}_k}$ $\mathbf{d}_{k+1} := \mathbf{r}_{k+1} + \beta_k \mathbf{d}_k$ k := k + 1end repeat return \mathbf{x}_{k+1} as the result

 $f \rightarrow \min_{x,y,z}$ Conjugate gradients (CG) method

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Convergence

Theorem 1. If matrix A has only r different eigenvalues, then the conjugate gradient method converges in r iterations.

Theorem 2. The following convergence bound holds

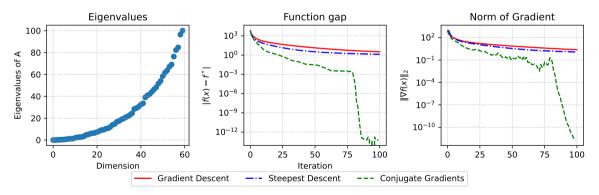
$$||x_k - x^*||_A \le 2\left(\frac{\sqrt{\kappa(A)} - 1}{\sqrt{\kappa(A)} + 1}\right)^k ||x_0 - x^*||_A,$$

where $||x||_A^2 = x^\top A x$ and $\kappa(A) = \frac{\lambda_1(A)}{\lambda_n(A)}$ is the conditioning number of matrix A, $\lambda_1(A) \ge ... \ge \lambda_n(A)$ are the eigenvalues of matrix A

Note: Compare the coefficient of the geometric progression with its analog in gradient descent.

$$f(x) = \frac{1}{2}x^T A x - b^T x \to \min_{x \in \mathbb{R}^n}$$

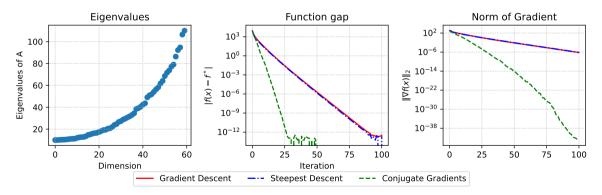
Convex quadratics. n=60, random matrix.



 $f \rightarrow \min_{x,y,z}$ Conjugate gradients (CG) method

$$f(x) = \frac{1}{2}x^T A x - b^T x \to \min_{x \in \mathbb{R}^r}$$

Strongly convex quadratics. n=60, random matrix.

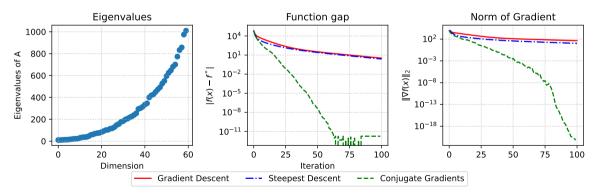


 $f \rightarrow \min_{x,y,z}$ Conjugate gradients (CG) method

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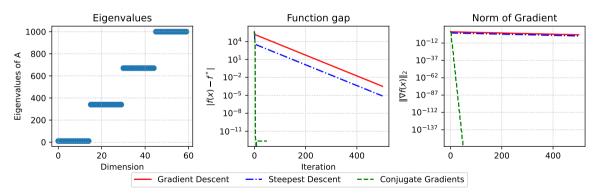
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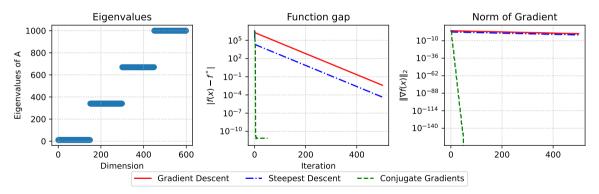
$$f(x) = \frac{1}{2}x^T A x - b^T x \to \min_{x \in \mathbb{R}^r}$$

Strongly convex quadratics. n=60, clustered matrix.



$$f(x) = \frac{1}{2}x^T A x - b^T x \to \min_{x \in \mathbb{R}^r}$$

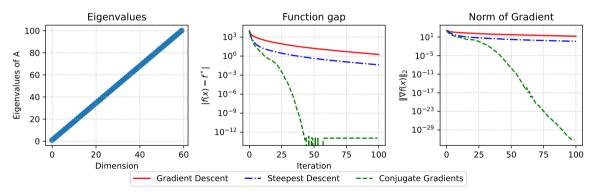
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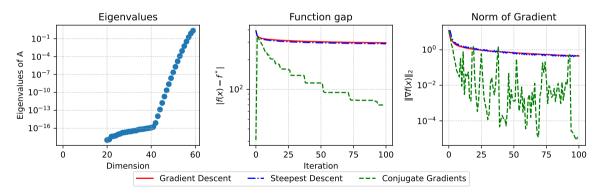
$$f(x) = \frac{1}{2}x^T A x - b^T x \to \min_{x \in \mathbb{R}^r}$$

Strongly convex quadratics. n=60, uniform spectrum matrix.



$$f(x) = \frac{1}{2}x^T A x - b^T x \to \min_{x \in \mathbb{R}^r}$$

Strongly convex quadratics. n=60, Hilbert matrix.



Non-linear conjugate gradient method

In case we do not have an analytic expression for a function or its gradient, we will most likely not be able to solve the one-dimensional minimization problem analytically. Therefore, step 2 of the algorithm is replaced by the usual line search procedure. But there is the following mathematical trick for the fourth point:

For two iterations, it is fair:

$$x_{k+1} - x_k = cd_k,$$

where c is some kind of constant. Then for the quadratic case, we have:

$$\nabla f(x_{k+1}) - \nabla f(x_k) = (Ax_{k+1} - b) - (Ax_k - b) = A(x_{k+1} - x_k) = cAd_k$$

Expressing from this equation the work $Ad_k = \frac{1}{c} (\nabla f(x_{k+1}) - \nabla f(x_k))$, we get rid of the "knowledge" of the function in step definition β_k , then point 4 will be rewritten as:

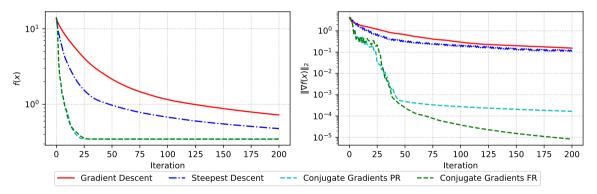
$$\beta_k = \frac{\nabla f(x_{k+1})^\top (\nabla f(x_{k+1}) - \nabla f(x_k))}{d_k^\top (\nabla f(x_{k+1}) - \nabla f(x_k))}.$$

This method is called the Polack-Ribier method.

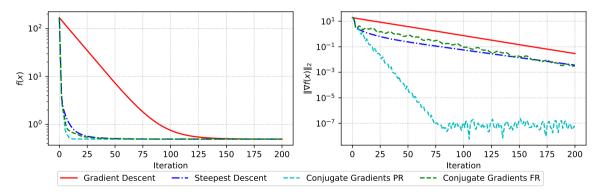
 $f \rightarrow \min_{x,y,z}$ Non-linear CG

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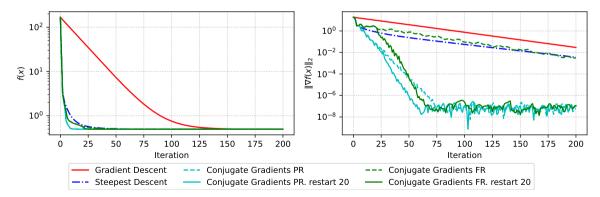
$$f(x) = \frac{\mu}{2} \|x\|_2^2 + \frac{1}{m} \sum_{i=1}^m \log(1 + \exp(-y_i \langle a_i, x \rangle)) \to \min_{x \in \mathbb{R}^n}$$



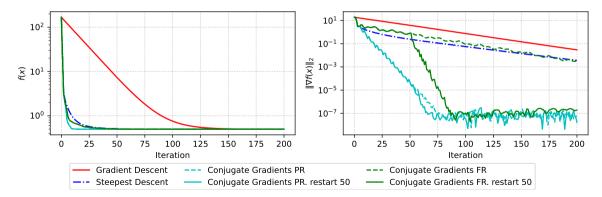
$$f(x) = \frac{\mu}{2} \|x\|_2^2 + \frac{1}{m} \sum_{i=1}^m \log(1 + \exp(-y_i \langle a_i, x \rangle)) \to \min_{x \in \mathbb{R}^n}$$



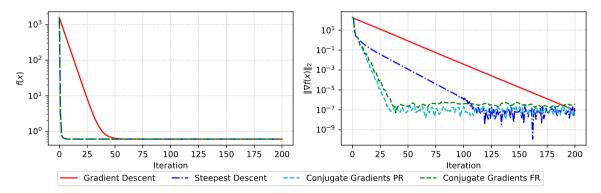
$$f(x) = \frac{\mu}{2} \|x\|_2^2 + \frac{1}{m} \sum_{i=1}^m \log(1 + \exp(-y_i \langle a_i, x \rangle)) \to \min_{x \in \mathbb{R}^n}$$



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